

1. (30 points) You have a glass with mass m bouncing off the floor. Its duration of contact with the floor—the time difference between first touching the floor and last touching the floor—is τ . Its velocity when it first touches the floor is v_{iy} , and its velocity as it launches off the floor is v_{fy} . If, at any time during its contact with the floor, the force on the glass ever exceeds F_{\max} , even for the tiniest fraction of a second, the glass will break. Note that the force on the glass during its collision with the floor will *not* be constant, and you have no idea what the exact force graph looks like.

- (a) Write down an inequality describing the condition under which it is certain that the glass *will* break. *Hint:* Sketching an F vs. t graph might help you think about this.

- (b) Let's say the inequality you wrote down does not hold. Does this mean that the glass is certain to remain unbroken? Explain.

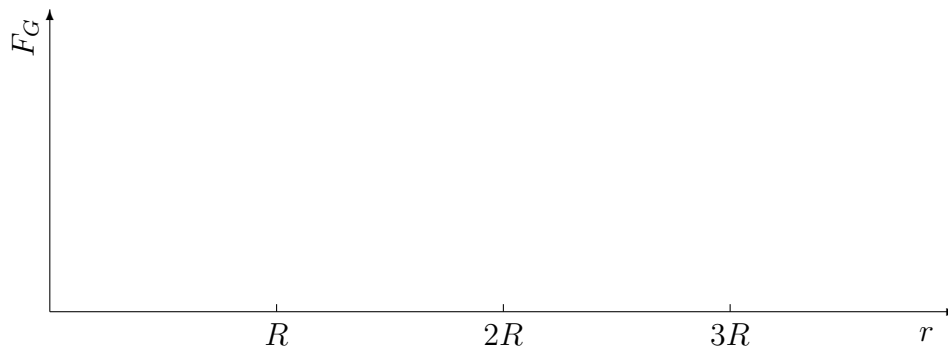
2. (30 points) You do a collision experiment with carts in the lab, but this time you work with expensive equipment that reduces friction with the track to a negligible level. You also work with carts that incorporate a spring that can be compressed and released during a collision, imparting the energy stored in the spring to the carts rebounding from the collision.

You set up the collision with a cart with mass $2m$ with initial velocity $v_{2i} = v$ heading toward a cart with mass m that starts at rest. You measure the final velocity of the cart with mass m in three different experiments, obtaining $v_{1f} = v$, $v_{1f} = \frac{4}{3}v$, and $v_{1f} = 2v$. Analyze these three experiments and determine which experiments must have had a compressed spring released during the collision.

3. (40 points) Remember how we got the gravitational potential energy mgh : the applied force acting against gravity had a magnitude of mg , and we found the area under the force-versus-distance curve, a rectangle of height mg and base h .

Now we want to generalize this to beyond locations close to the Earth's surface. Take the gravitational force magnitude F_G between two point masses m_1 and m_2 separated by a distance r . We will again look at the area under the force-distance curve.

(a) Sketch a graph of F_G versus r .



Now, according to your sketch, do you do more work in changing r from R to $1.1R$, from $2R$ to $2.1R$, or from $3R$ to $3.1R$?

(b) The convention for gravitational potential energy is to say that it is zero when the masses are infinitely far from each other. So the expression for U_G must become very small as r becomes large. Given this, and the behavior you found in part (a), which of the following is the correct general equation for U_G ? (Only one of the options given is consistent with what you found about U_G .)

(i) $U_G = \frac{1}{2}Gr^2$

(ii) $U_G = m_1m_2r$

(iii) $U_G = \frac{m_1}{m_2}e^{-Gr}$

(iv) $U_G = -\ln Gr$

(v) $U_G = -Gm_1m_2/r$

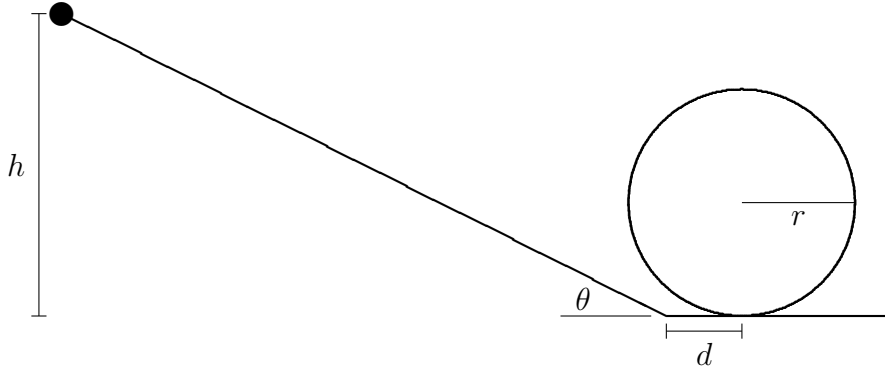
Show your work checking consistency:

(c) Given your U_G , find the escape speed of an object launched away from Earth. This is the minimum speed necessary to never fall back to Earth under the influence of gravity: You start from r equal to the radius of Earth and speed equal to your escape speed, and end up at r equal to infinity and the object at rest. You can look up data about the Earth to find a numerical result.

(d) Find an equation for the radius r_s for the event horizon of a black hole with mass m . The event horizon marks the point beyond which nothing can return, since it would have to travel faster than light. You find r_s by setting the escape speed equal to the speed of light c .

Extra Problems (not graded)

4. (0 points) A roller coaster cart starts from an initial height h , goes downhill at an angle θ with the horizontal, travels a horizontal distance d , and goes through a loop with radius r .

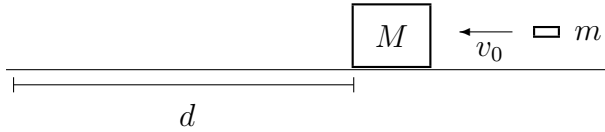


- (a) Assuming dissipative forces such as friction and drag are negligible, what is the minimum height h_{\min} for the cart to be able to complete the loop?

(b) Assume that the cart loses energy to dissipative forces at a rate of ε per length of track traveled: if, for example, it travels a distance l , then $E_{\text{loss}} = \varepsilon l$. In that case, what would h_{min} now be?

(c) Describe the ways in which the assumption of losing ε per length traveled, regardless of the orientation of the track, is not completely accurate.

5. (30 points) You decide to design a variation on the idea of a ballistic pendulum. You keep the part with a bullet with mass m and initial velocity v_0 embedding in a block of mass M . But after that totally inelastic collision, instead of having the bullet-block combination swing upwards on a pendulum, you let it slide on a rough and flat surface, with a coefficient of kinetic friction μ_k . You wait for the bullet-and-block to come to a stop, and measure the distance d it traveled from the point where the bullet first struck the block.



- (a) Find an equation for v_0 . *Hint:* Think about how to account for the work done by friction, which will give you the energy loss.

- (b) Assume you will use your setup to measure bullet speeds of around $v_0 = 500$ m/s, with bullet masses around $m = 0.01$ kg. Other reasonable values would be $\mu_k = 0.5$ and $d = 1.0$ m, which is practical to measure in the lab. What, then, would the block mass M have to be in your setup?